

Motivation

The **value of and interest into trajectory data** are increasingly apparent. Traffic management, urban planning, and routing advice are just a few of its many applications. Yet, it entails **extensive privacy risk**, as trajectory data is extremely privacy-invasive. Unfortunately, several conditions **complicate the anonymization of trajectory data**: They are sequential, high-dimensional, bound to geo-physical restrictions, and easily mapped to semantic POIs.

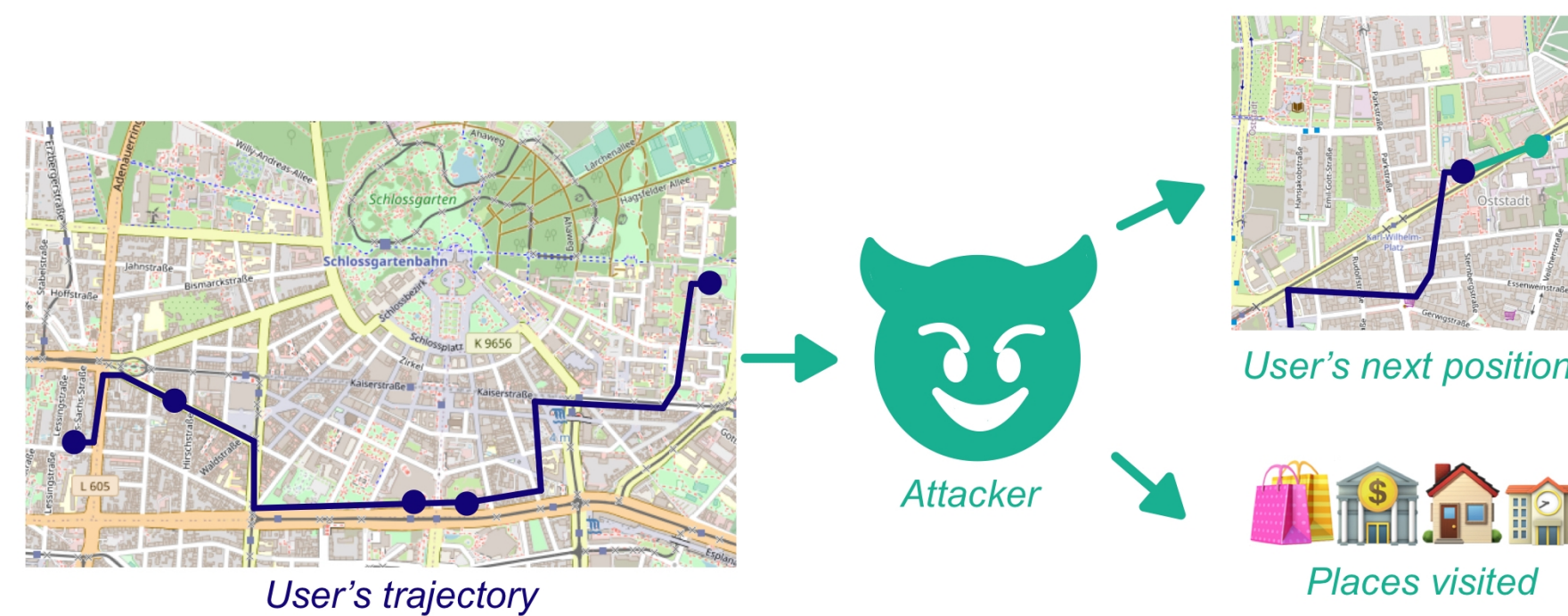
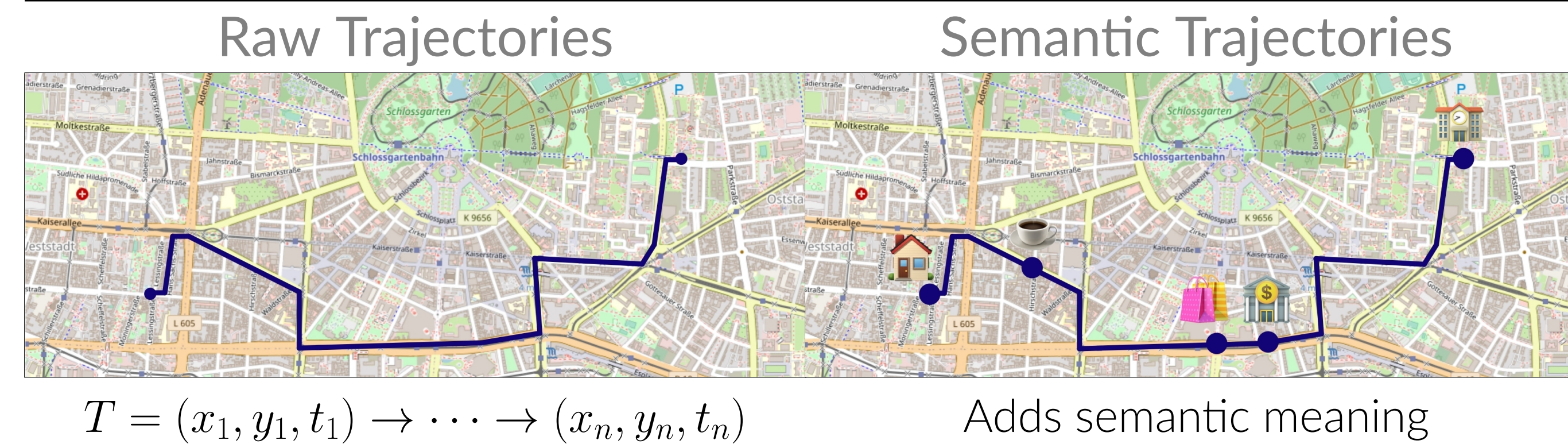
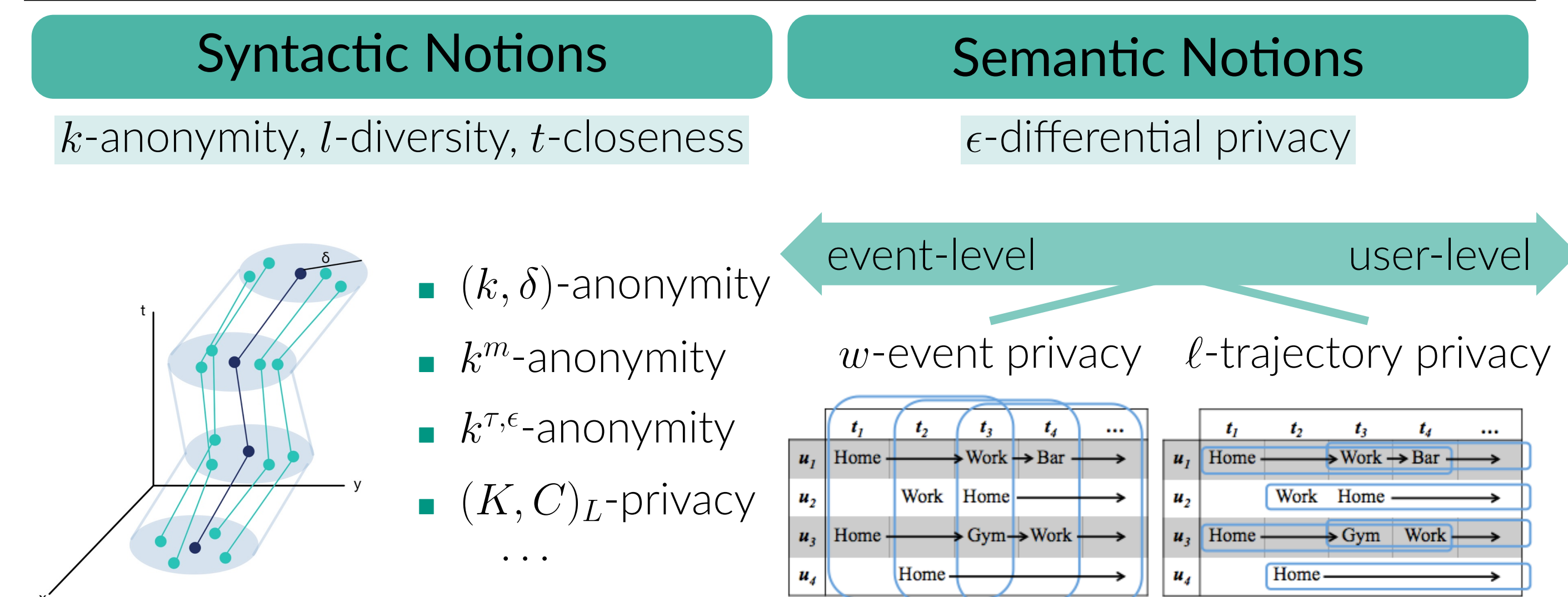


Figure 1. Trajectories may reveal accurate behavioral patterns, allowing attackers to infer sensitive aspects of an individual's life, including health status, religious beliefs, social relationships, or sexual preferences.

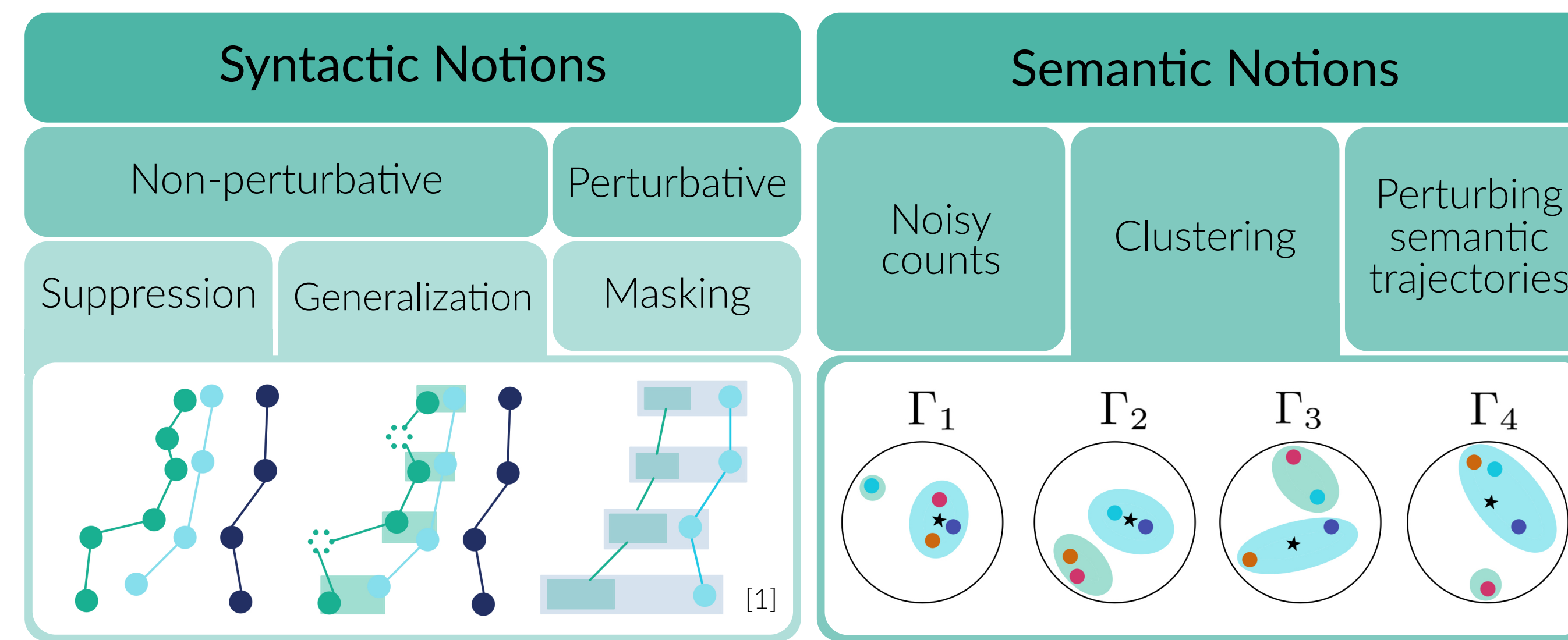
Trajectories and Data Sets



Measuring Privacy

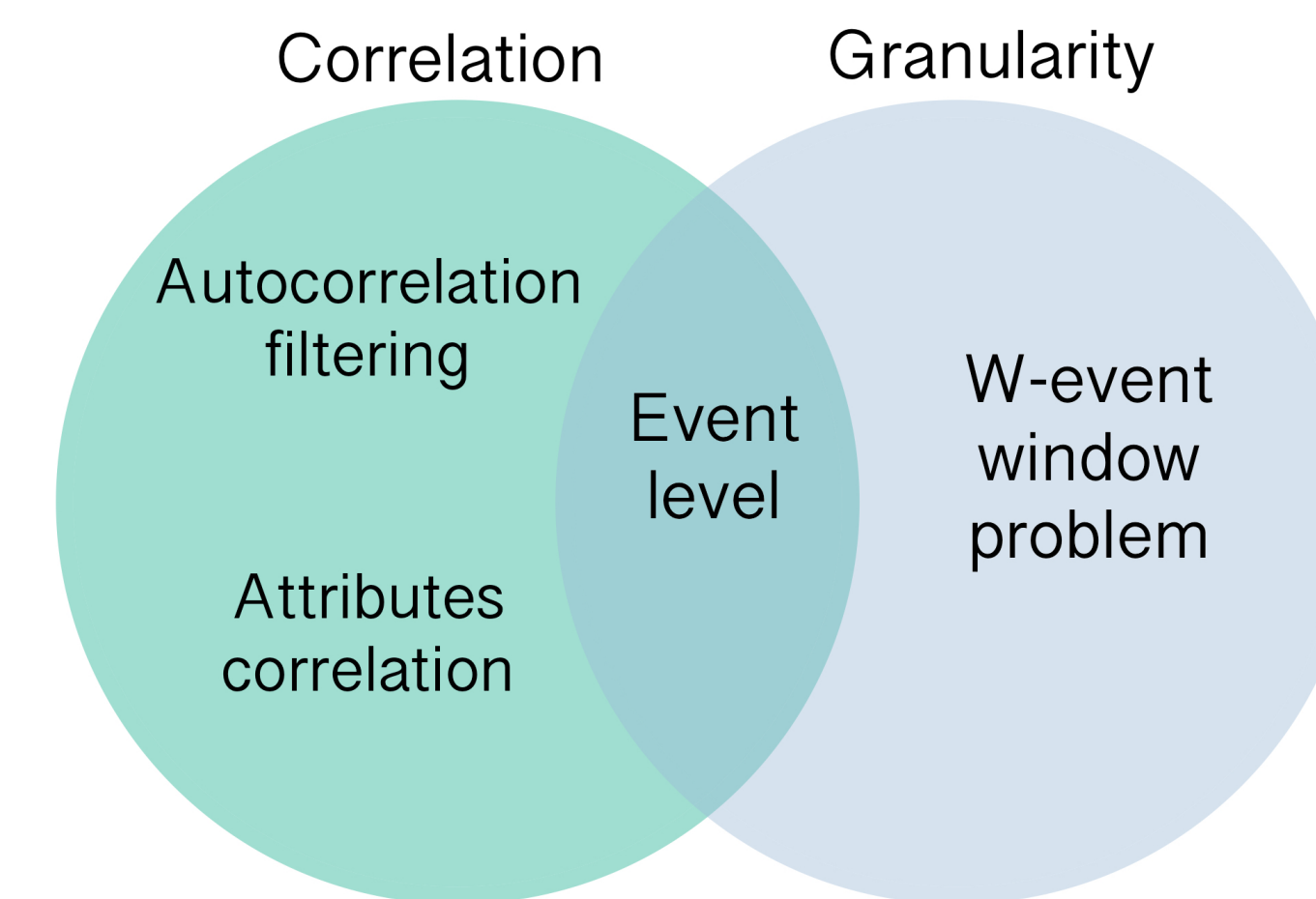


Mechanisms: Achieving Privacy



Privacy Limitations

Shortcomings of semantic notions' privacy guarantees



Limitations in the presented mechanisms

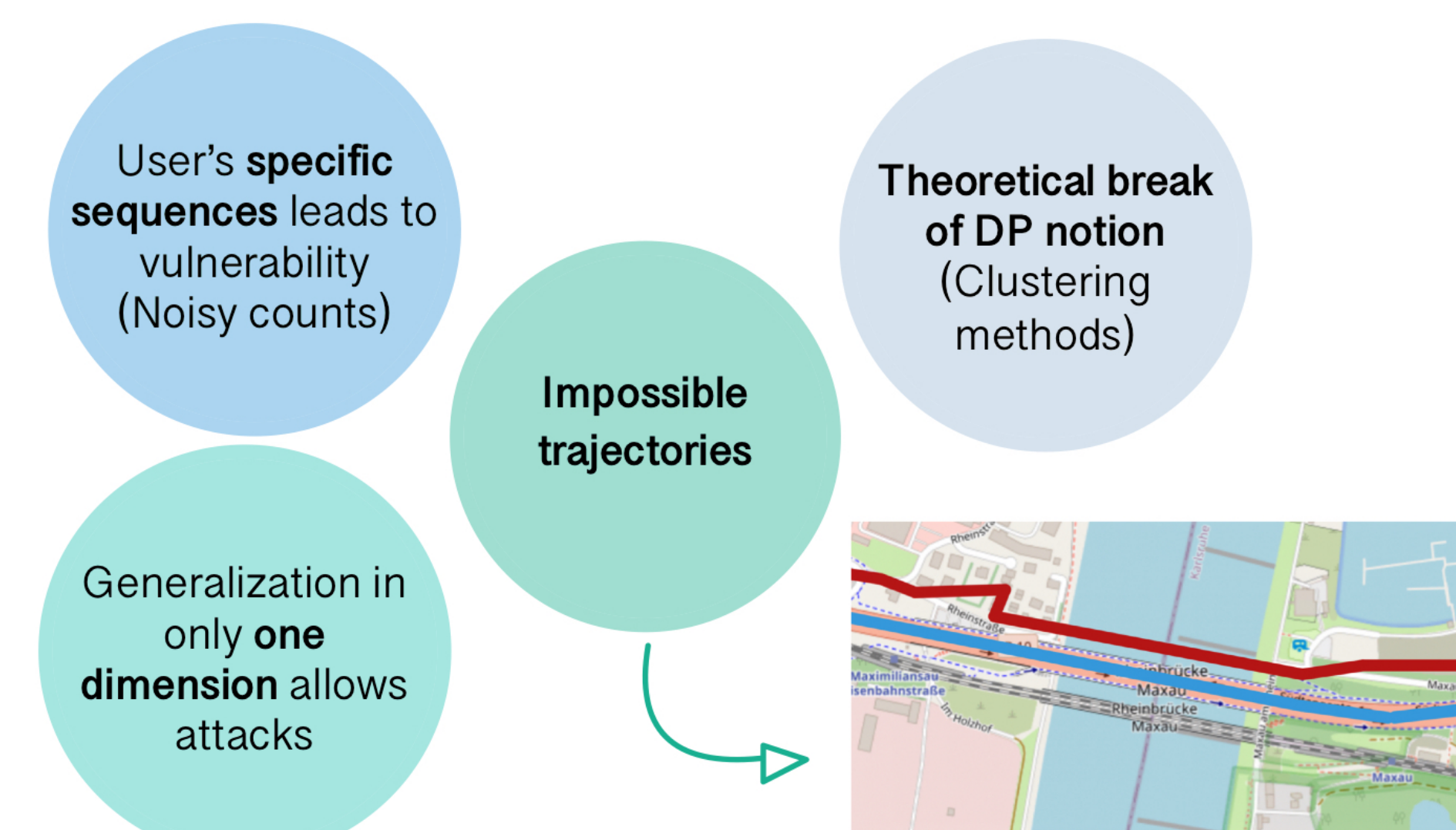
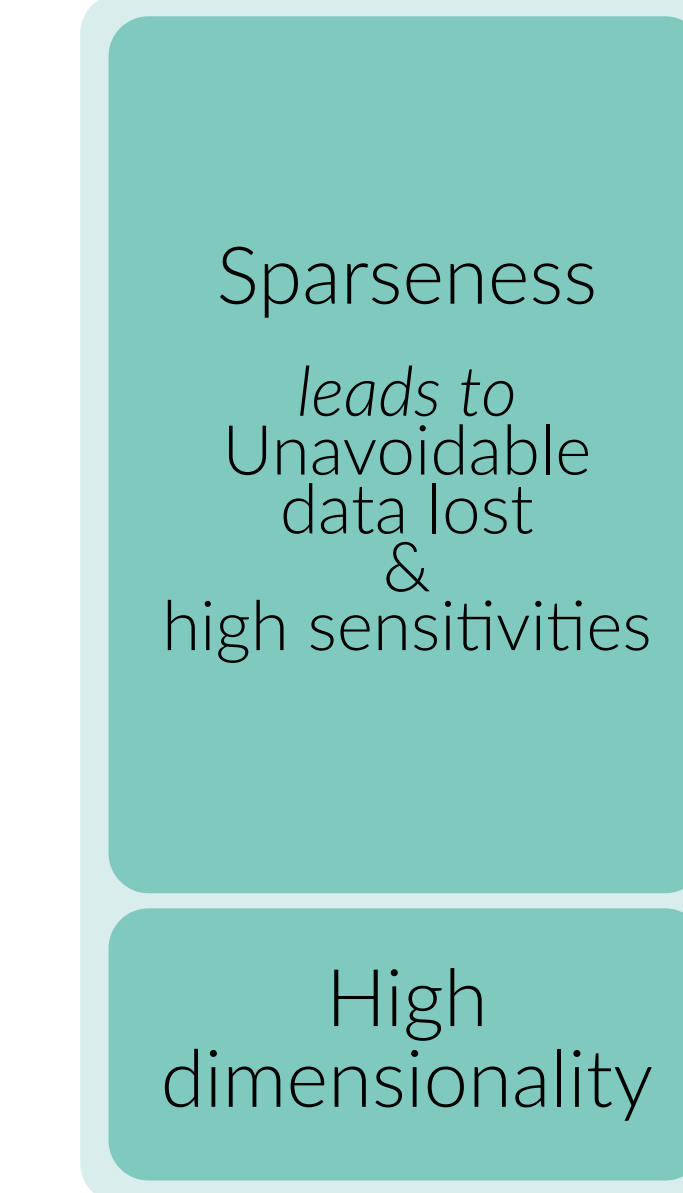


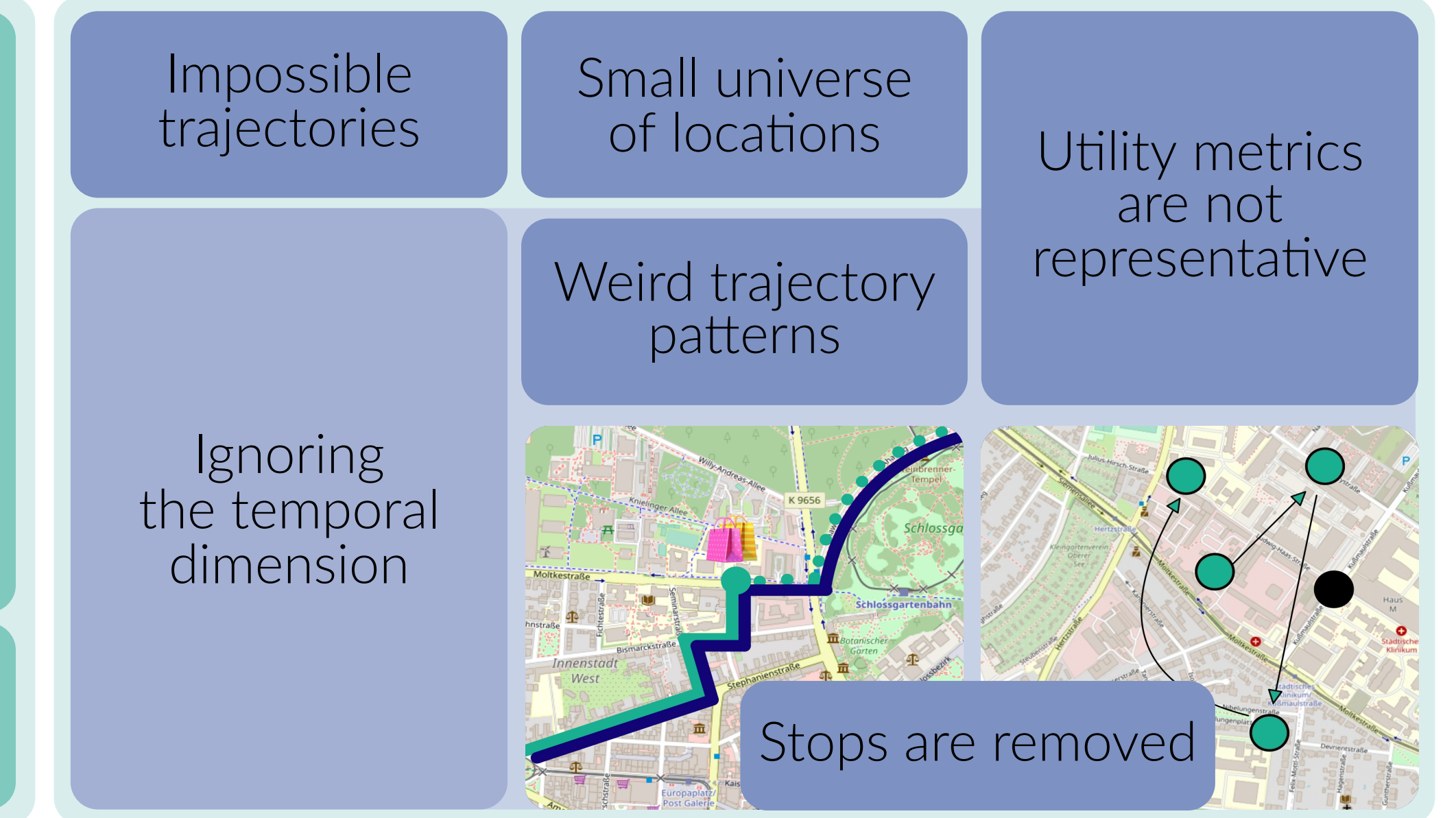
Figure 2. ■ corresponds to an impossible trajectory after sanitation process. With background knowledge (a map), we can rebuild the original trajectory easily.

Utility Limitations

Inherent properties of trajectory data



Problems of current proposals



Opportunities and Future Work

- Development of clustering algorithm for **entire trajectories** that takes the **temporal dimension** into account. High-dimensional topological clustering based on persistent homology will be interesting because of its qualitative predominance and its low computational cost.
- Adaptation of **alternative notions of privacy** that have been proposed to overcome deficiencies of DP against correlations. Creation of new axiomatic notions of privacy and corresponding mechanisms that meet guarantees.
- Consideration of **public knowledge** to reduce privacy budget consumption and avoid impossible results.
- Revision and selection of **proper utility metrics** that ensure their applicability.

Acknowledgments & References

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Map screenshots from © OpenStreetMap contributors [2].

[1] M. E. Nergiz, M. Atzori, Y. Saygin, and B. Güç, "Towards trajectory anonymization: a generalization-based approach," in *SPRINGL '08*, 2008.

[2] OpenStreetMap contributors, "Planet dump retrieved from <https://planet.osm.org>," <https://www.openstreetmap.org>, 2022.